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Nagoya, March 2002

SySal



Motivation
Basic Ideas
Implementation
DAQ Clusters
SySal at Work

SySal (System of Salerno) was born to:

- Reproduce the human way of scanning
- Recognize all tracks regardless of their slope
- Yield the maximum detail level of the information stored in the emulsion (i.e. track grains)
- Automate analysis to the maximum degree, leaving only Physics tasks to humans
- Software-based approach allows flexibility
- Scan fast and efficiently
- Use commercial, turn-key hardware whenever possible

The original ideas of SySal date back to 1994

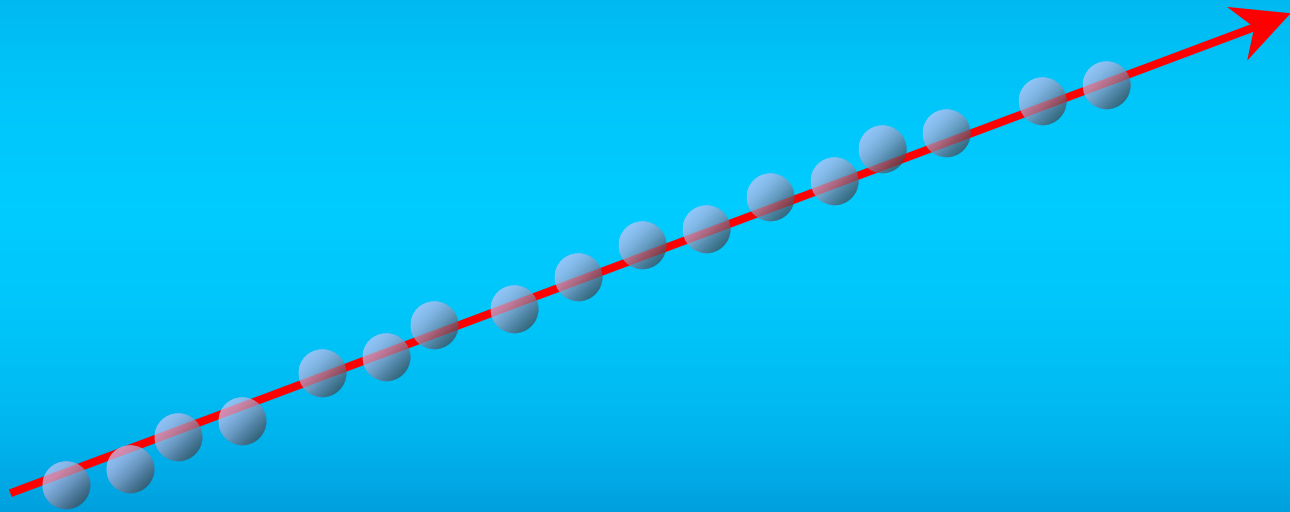
Working system started producing data in Dec. 1996

First multitracking system

Improvement and development continues...

Basic Ideas

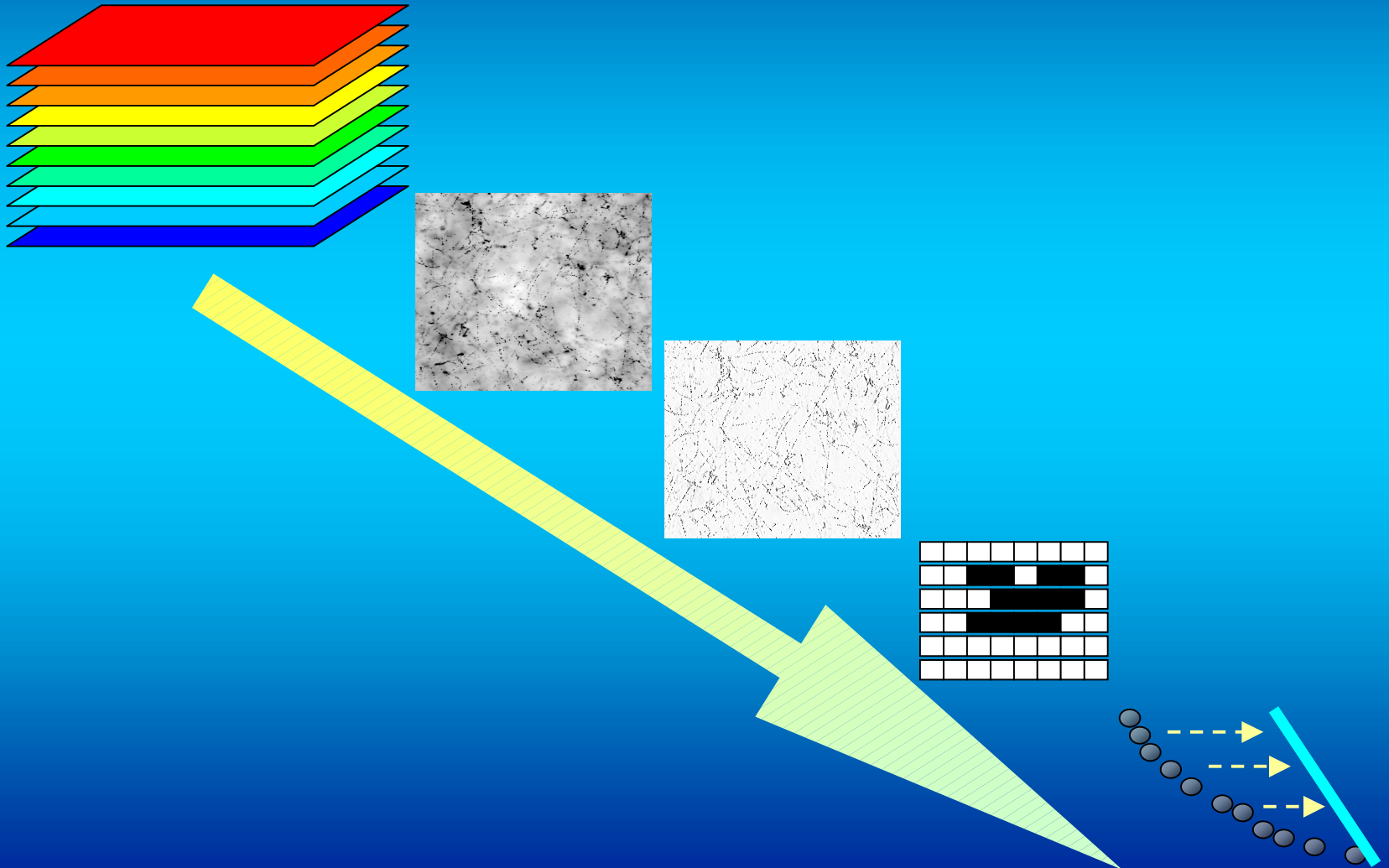
After the passage of an ionizing particle, the development process leaves a path metallic silver grains: the “track”



Knowing the exact position and shape of each grain gives the highest level of detail present in the emulsion

Basic Ideas

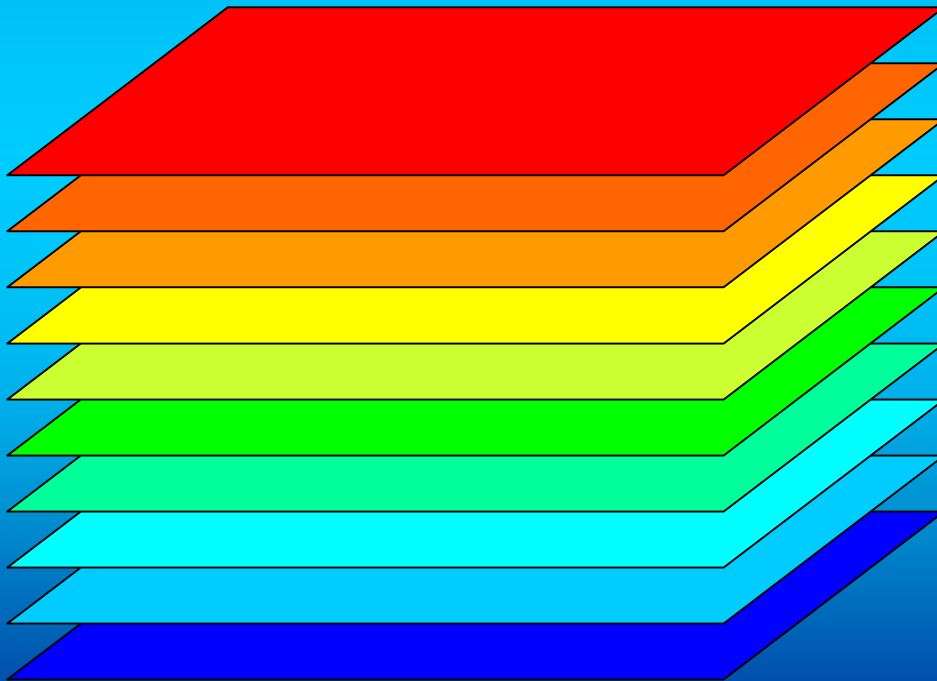
The data taking process involves several steps



Basic Ideas

For each FOV (field of view) we take several tomographic images of the emulsion

The camera axis (Z) moves during data taking, but an electronic shutter allows to obtain almost still images of each layer



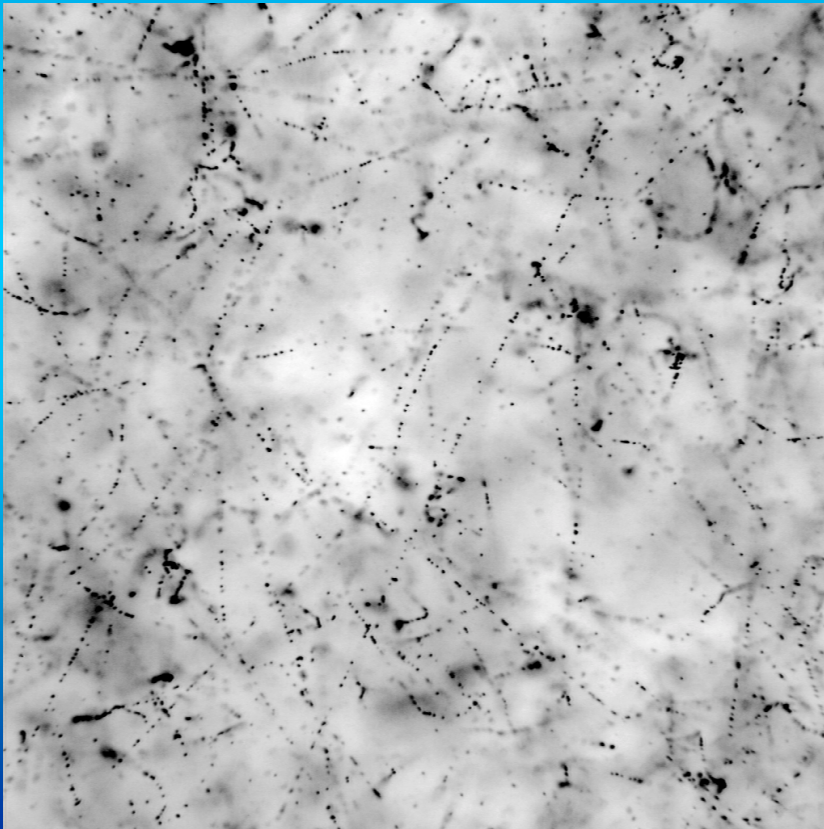
Volume scanning: the number of layers varies in order to cover the full thickness (20÷60 layers)

1 MPixel camera @ 30 fps
Wide FOV (200÷300 μm)

Basic Ideas

Images are grabbed by a commercial vision processor (currently we're using Matrox Genesis)

Clever image handling is crucial to obtain good results



~1000 background grains (fog +
cosmics + Compton electrons) and
~10 track grains...

Completely indistinguishable in a
2D image!!!

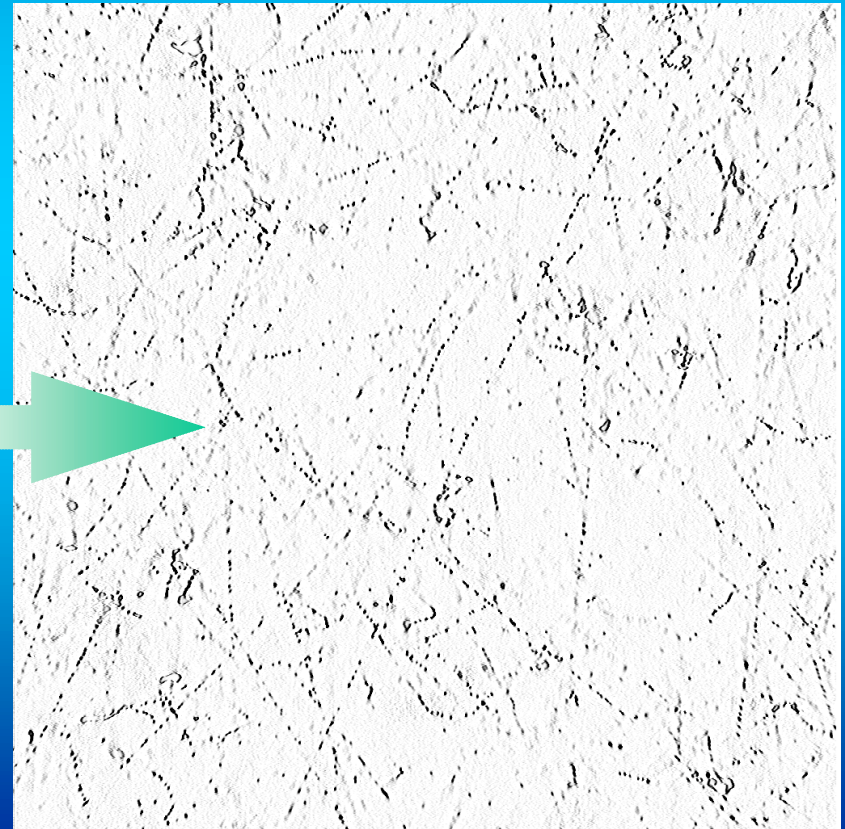
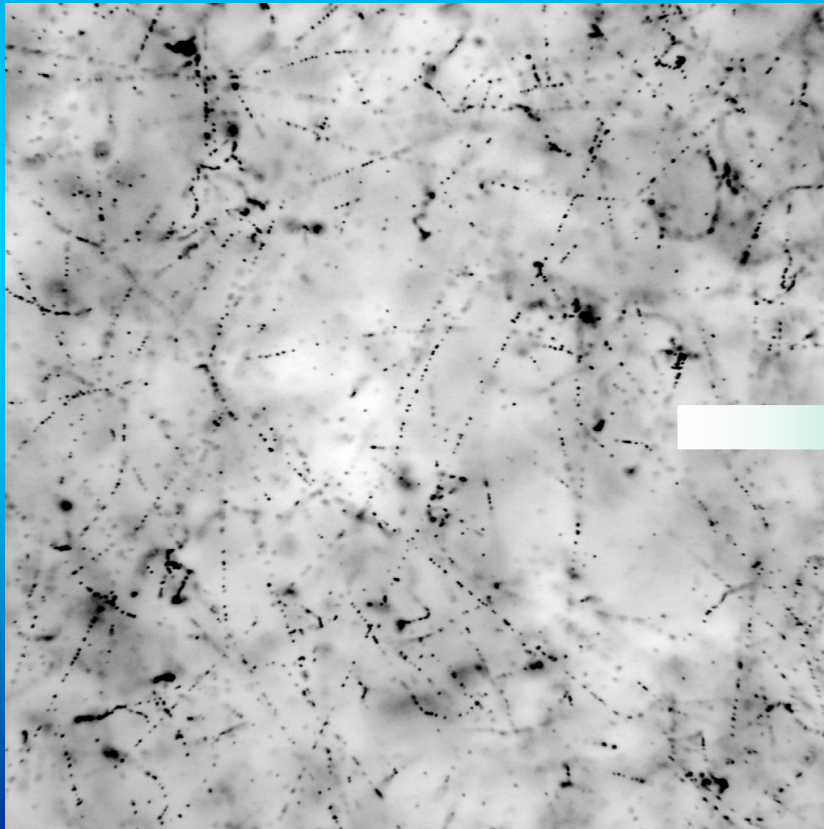
The image has lighter and darker
zones because of shadows from
neighboring layers

200×200 μm^2 in a CHORUS Target Sheet

Basic Ideas

Simple gray level threshold does not work...

A 2D FIR filter yields much better results



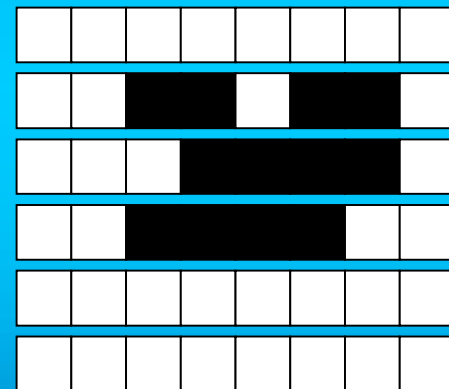
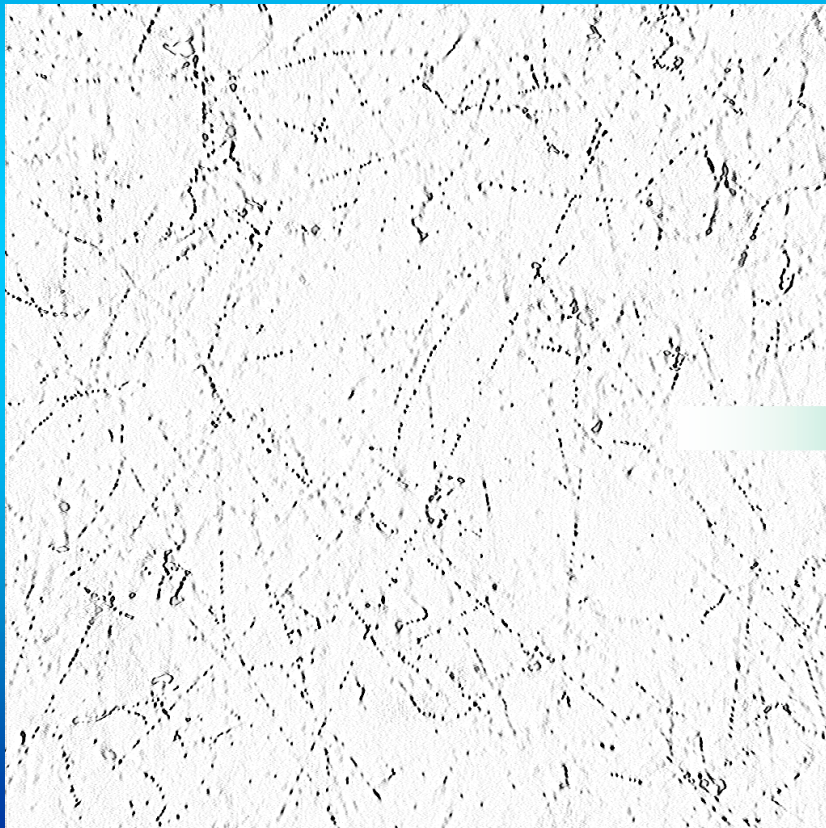
200×200 μm^2 in a CHORUS Target Sheet

Genesis filters on the fly

Basic Ideas

After filtering, a threshold is applied to the filter response, and pixels are marked as “black” or “white”

Cluster recognition proceeds on the host PC CPU

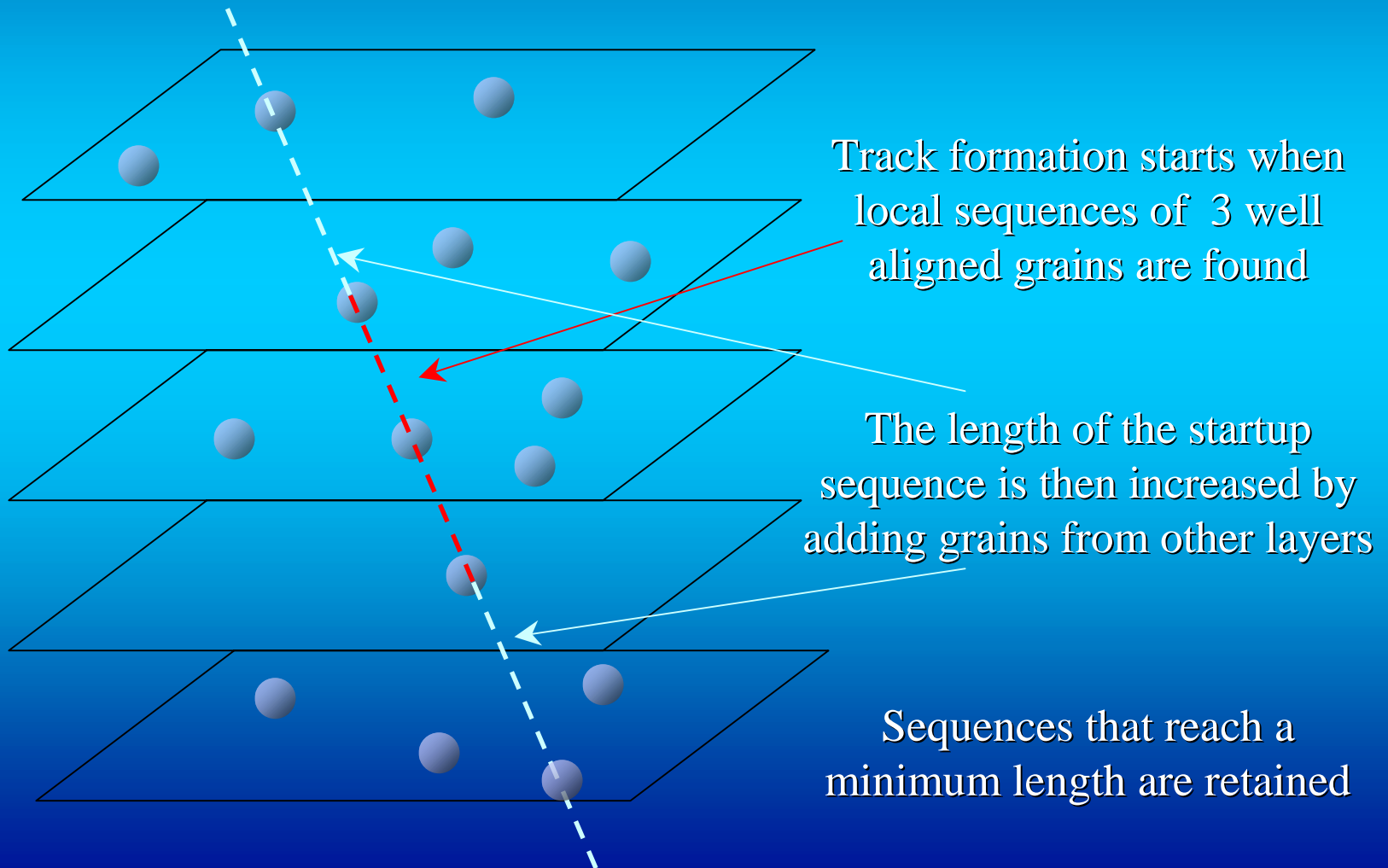


Horizontal black segments are assembled to form black clusters
Area and shape parameters are retained

$200 \times 200 \mu\text{m}^2$ in a CHORUS Target Sheet

Basic Ideas

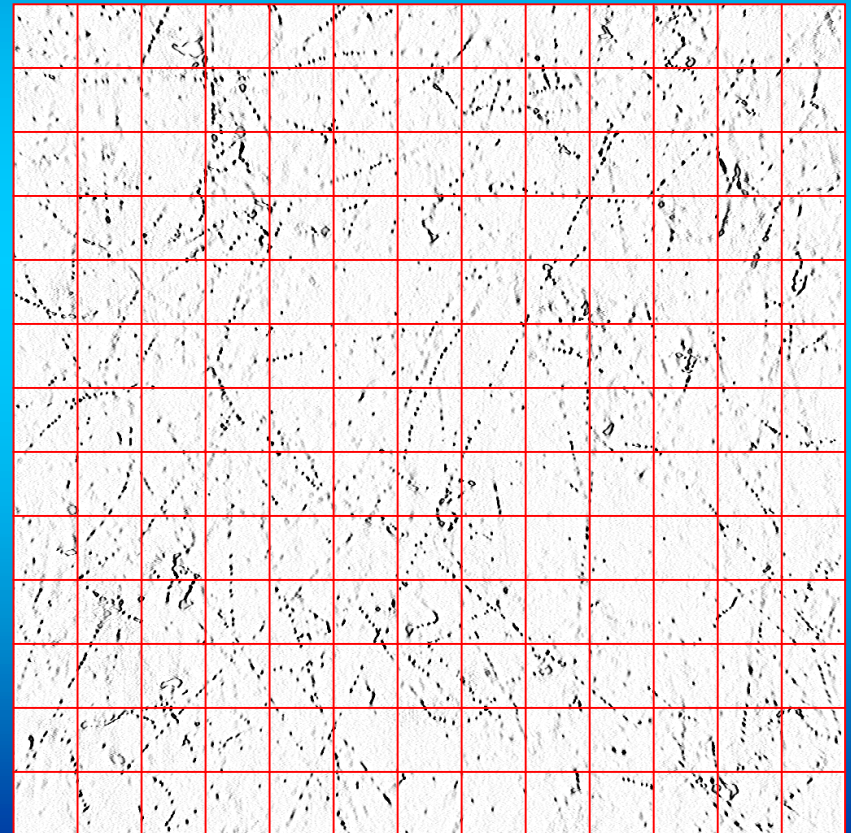
Tracking selects grains with appropriate shape and size and searches for 3D sequences of aligned grains



Basic Ideas

In order to reduce the combinatorial complexity, each 2D image is divided in a matrix of cells

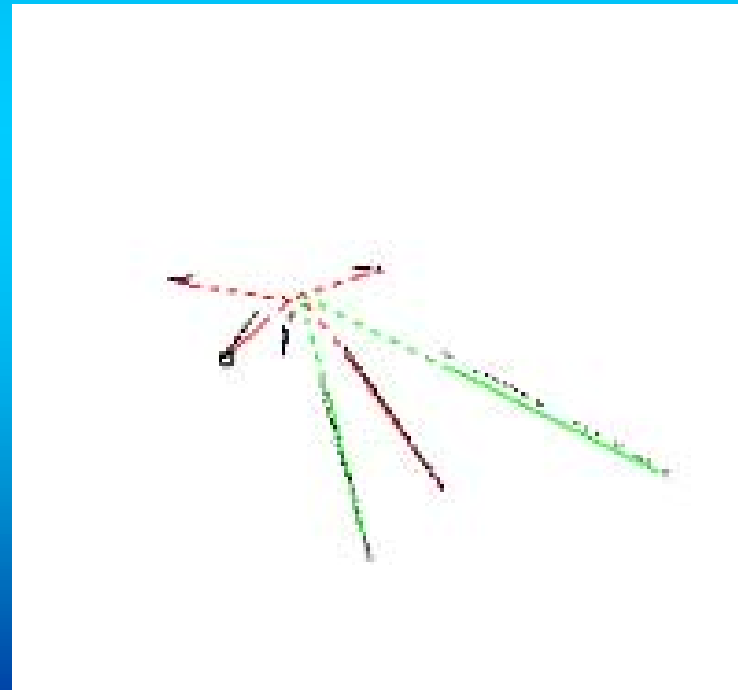
Tracking searches are performed using only a few cells at each iteration rather than the full image: a search shortcut that causes no efficiency downgrading



Automatic decay/interaction vertex recognition

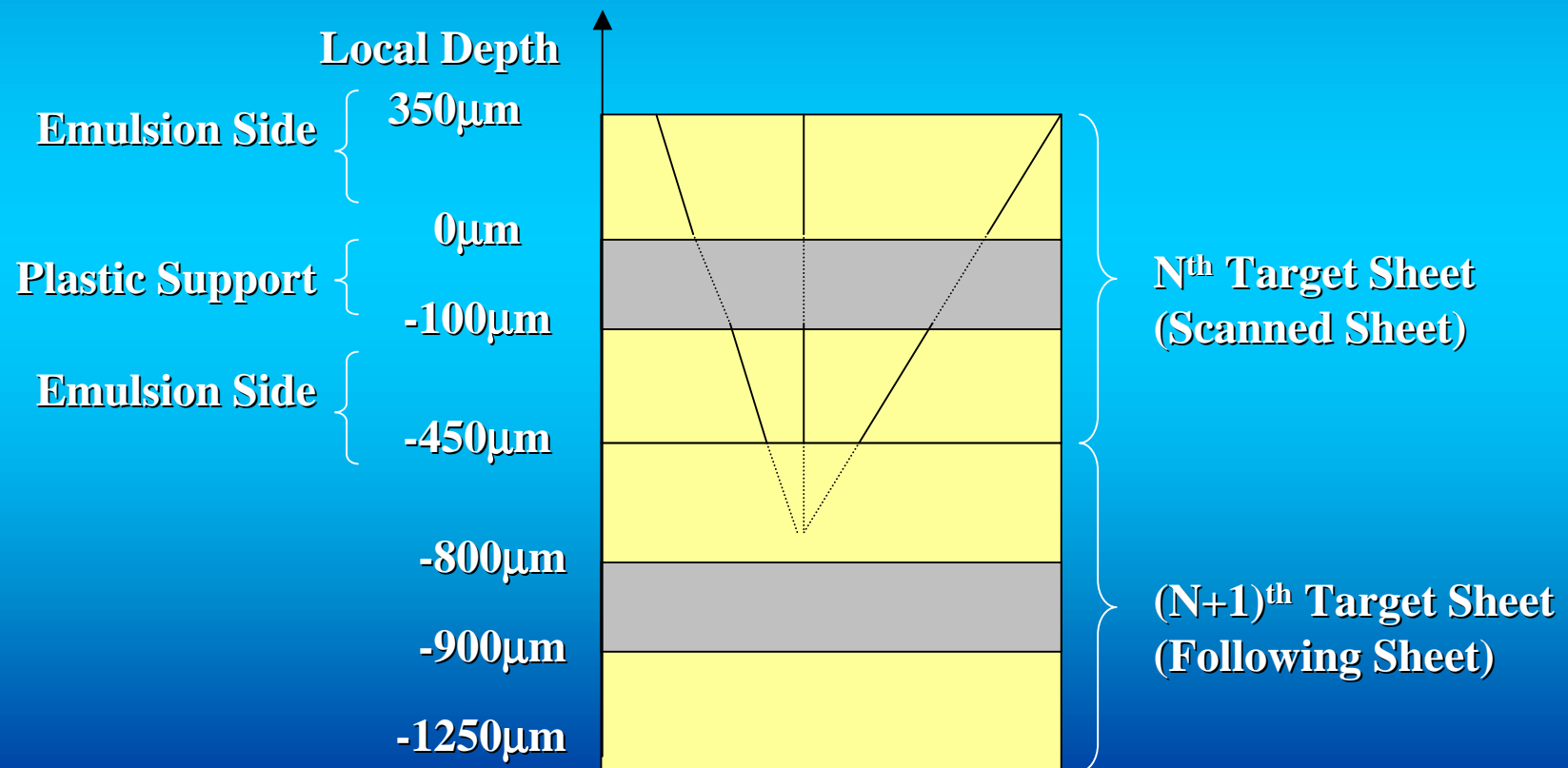
Since SySal reconstructs all tracks in a FOV, it is possible to check whether two or more trajectories cross at a common 3D point

Track crossing measurement is very precise because 3D grain positions are known



Automatic decay/interaction vertex recognition

It is often possible to detect a vertex located in another plate



Implementation

Stage: Nikon, MICOS

Motors: VEXTAStep RFK

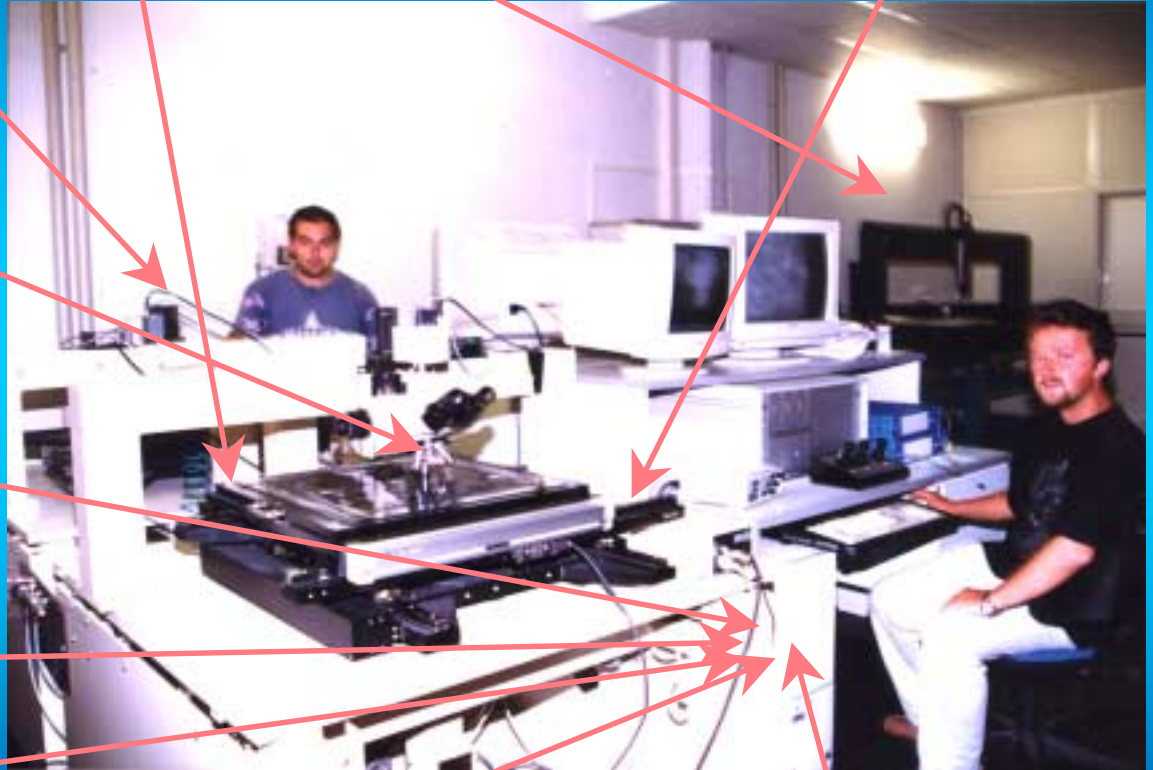
Camera: Hitachi KP-F110

Objective:
Tiyoda 50×, Leitz 22×

Host PC:
Pentium I – II – III – IV

Operating System:
Windows NT – 2000 – XP

DAQ Software: SySal 1.0

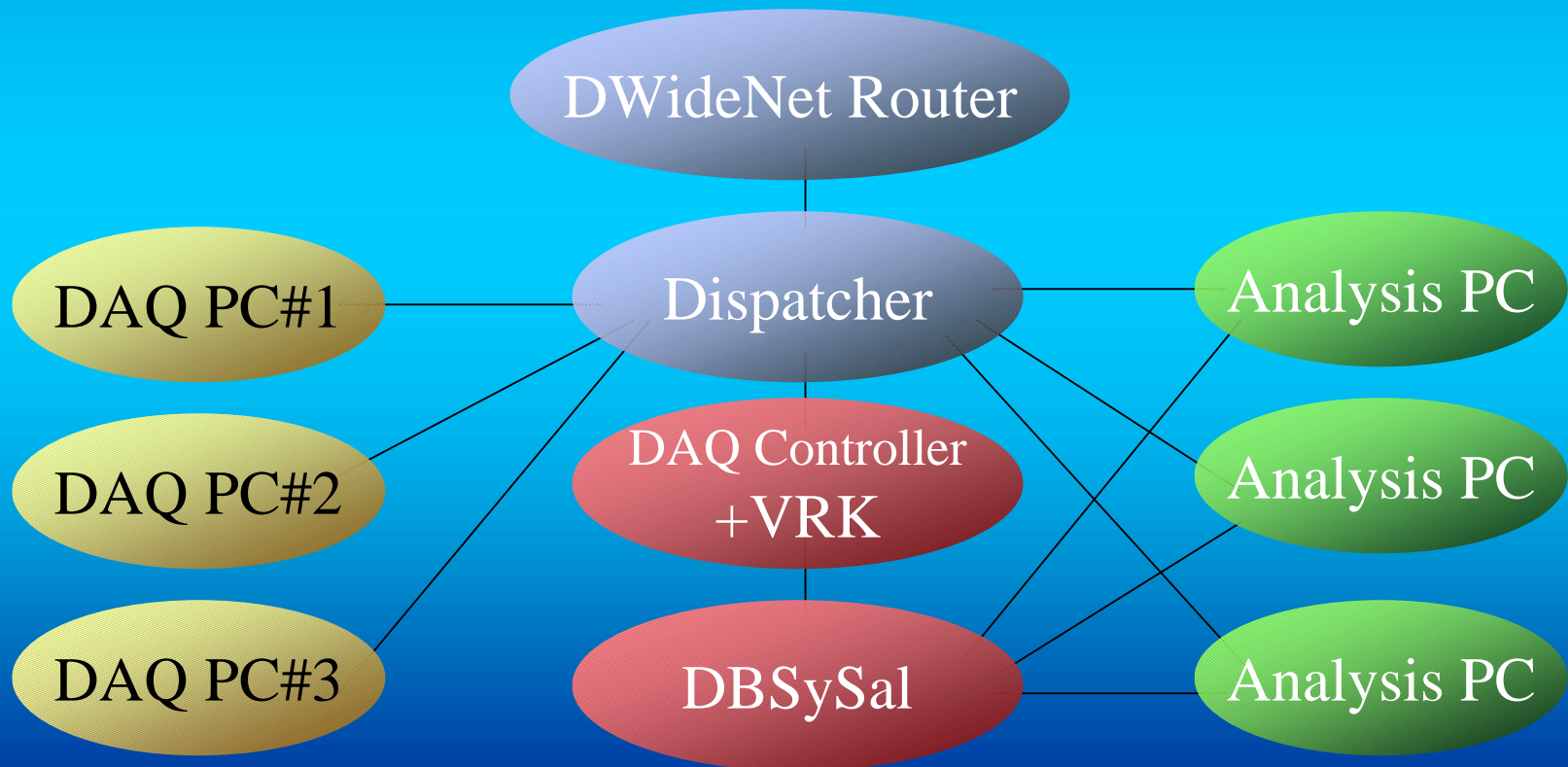


Vision Processor: Matrox Genesis

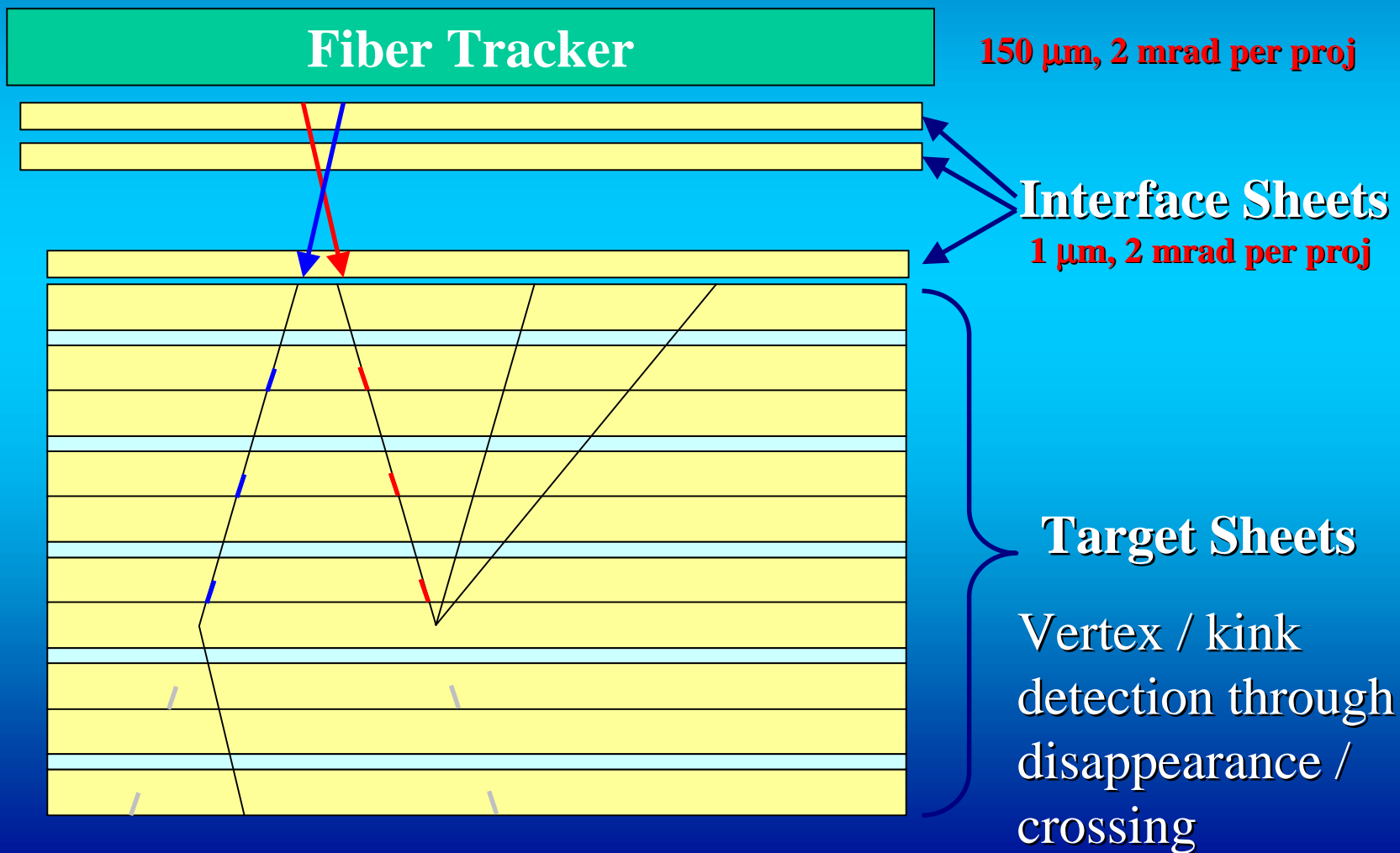
Motor Controller: National Instruments FlexMotion

SySal DAQ Clusters

SySal is seldom implemented as a single stand-alone DAQ machine, because of course this would limit the number of tasks one could perform with a certain data set



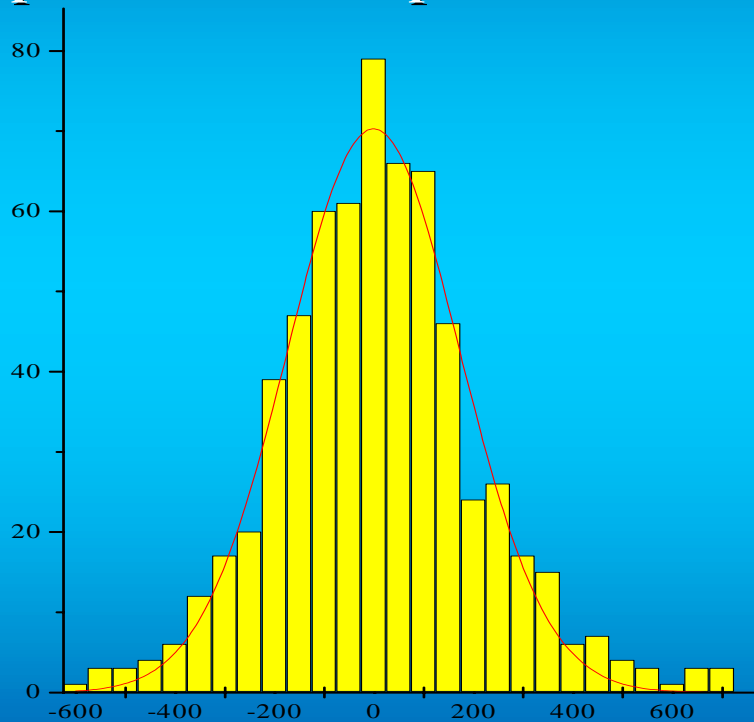
SySal in CHORUS: Scan-back + Total Scan (next talk)



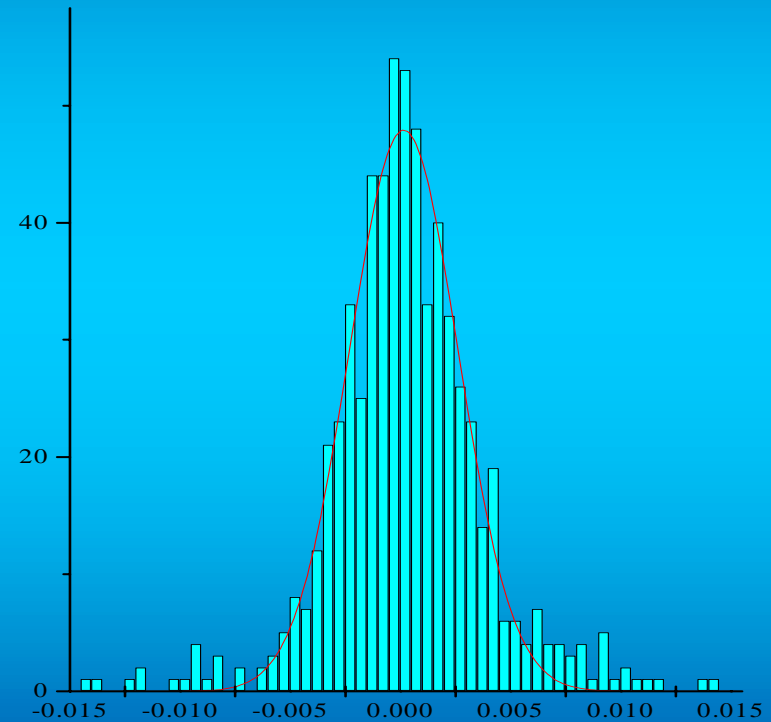
SySal in CHORUS: Scan-back on interface sheets (CS233T)

Efficiency on μ 's: $\sim 90\%$ (also includes TT fakes)

Speed: 500–700 predictions / day



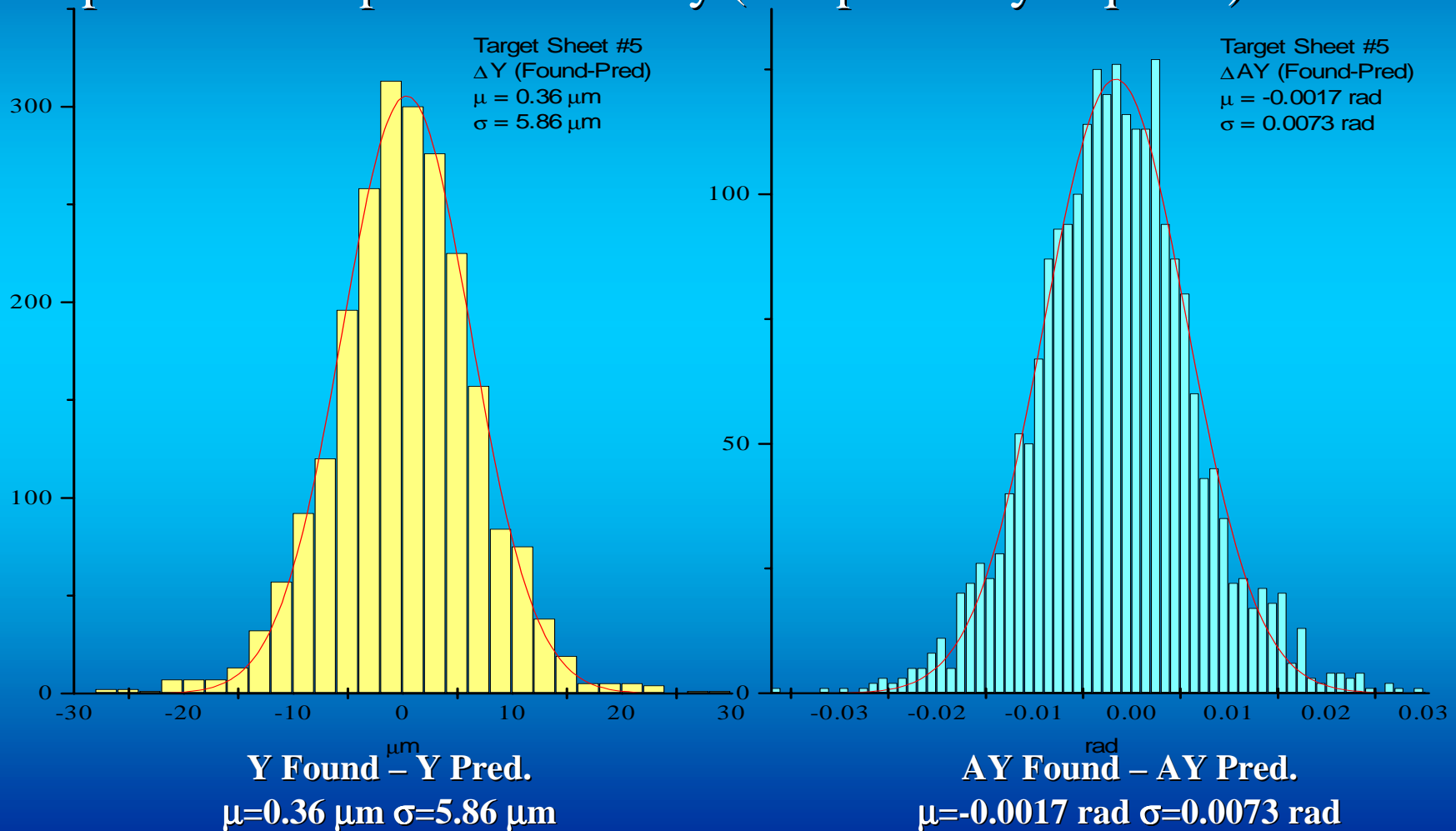
Z Found – Z Pred.
 $\mu = -1.2 \mu\text{m}$ $\sigma = 173.2 \mu\text{m}$



AZ Found – AZ Pred.
 $\mu = 0.0002 \text{ rad}$ $\sigma = 0.0025 \text{ rad}$

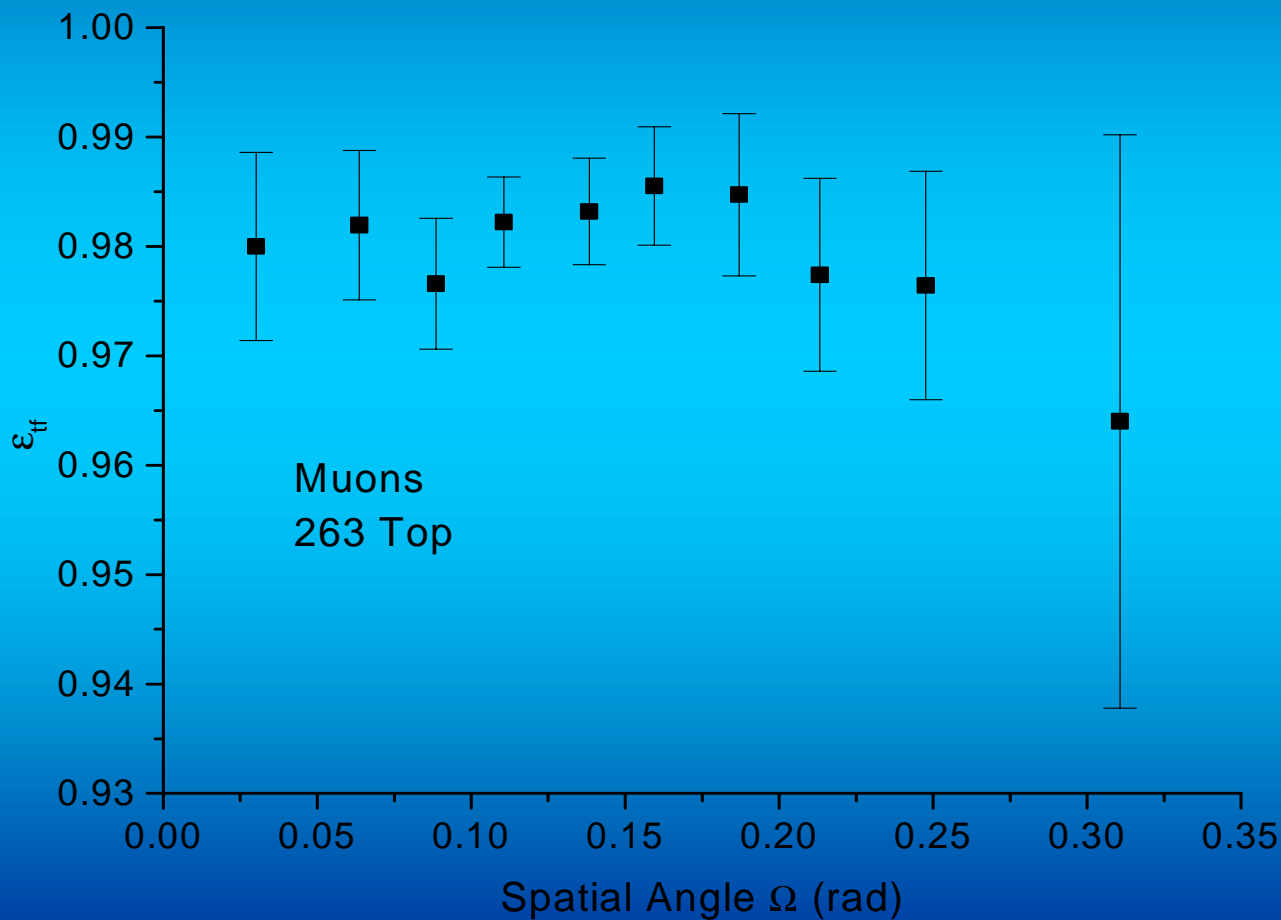
SySal in CHORUS: Scan-back on target sheets

Speed: ~4000 predictions / day (one pass only required)



SySal in CHORUS: Scan-back on target sheets

Finding efficiency on Target Sheets



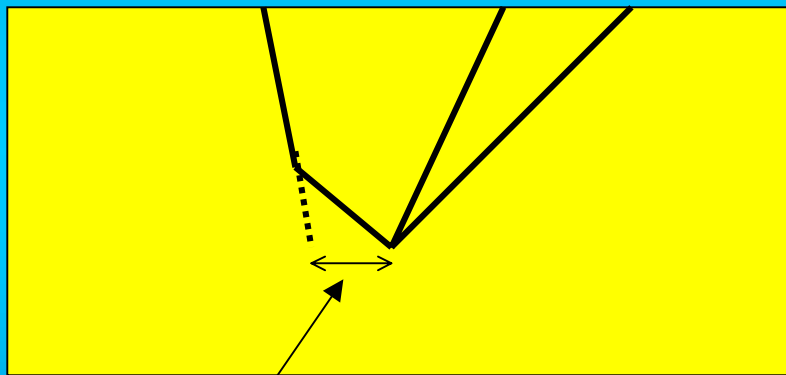
The DAQ Controller runs VRK on data files to obtain automatic analysis before putting them into the scanning DB (DBSySal)

The VRK (Vertex Reconstruction Kit) plug-in is able to reconstruct and measure interaction vertices while the scanning batch is in progress

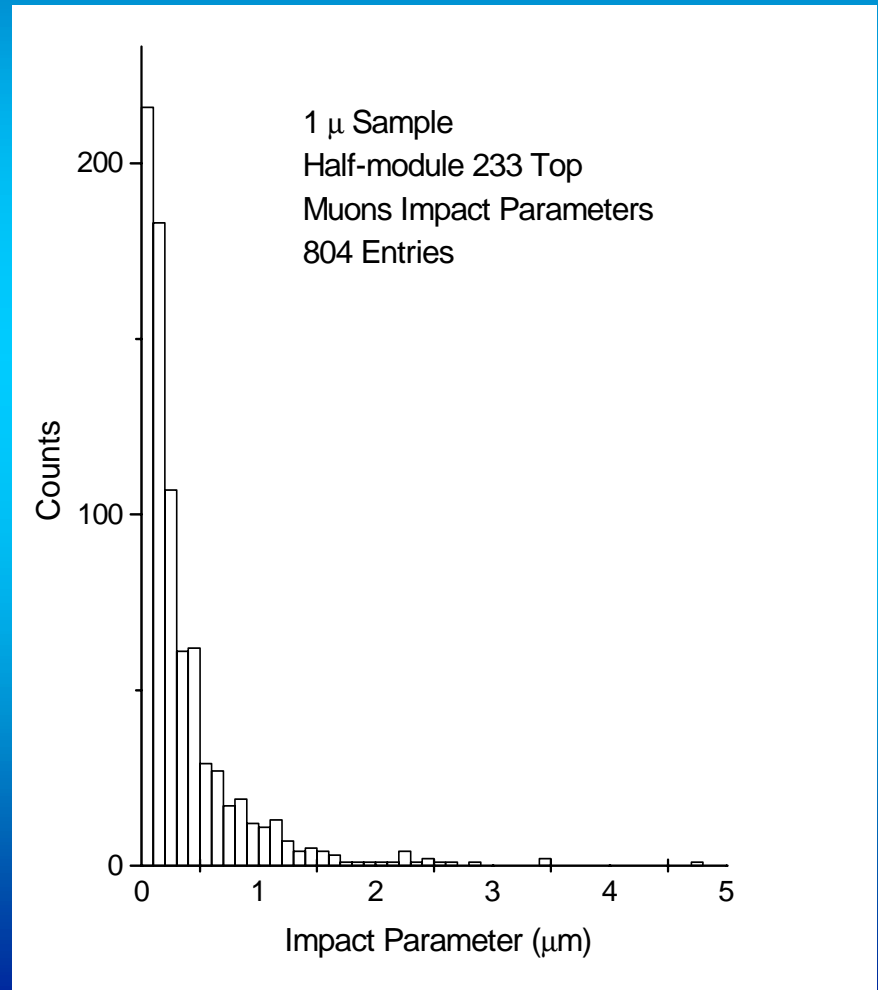
When a vertex / kink alarm is issued, a request to take a tomographic sequence of photos of the vertex zone is scheduled into the scanning batch

Output: ≈ 5 k Events (up to now) + a neutrino interaction image library

Precision of vertex reconstruction: the Impact Parameter method

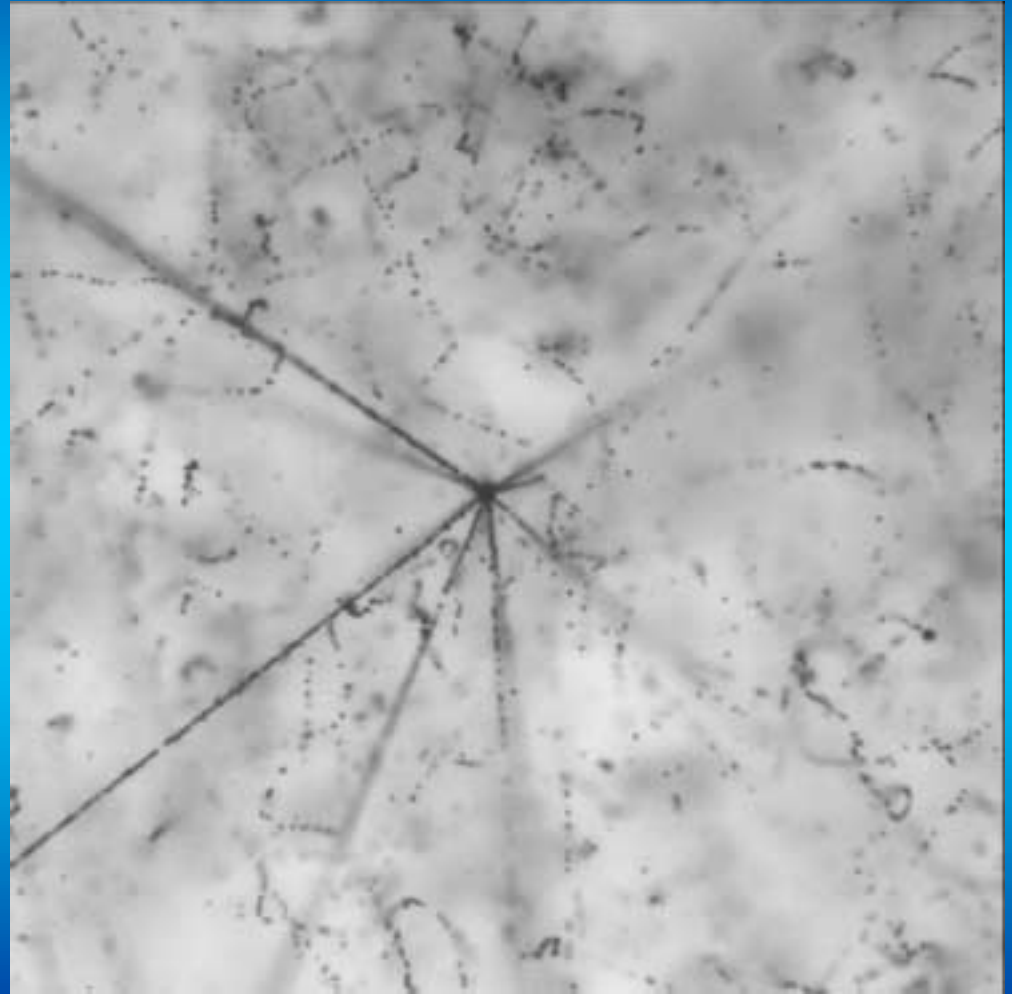


IP



We have ≈ 2 k 3D Images
of neutrino interactions

Manual checks are
possible without
physically being at the
microscope



SySal in CHORUS: also non-oscillation physics

Charm hunting

Special events (e.g. Charm production by anti- ν)

Search for hyperfragments / superfragments (new – listen to talk on black tracks!)

Momentum measurement through multiple scattering
(dedicated talk)

SySal in OPERA: Total Scan (next talk) for test exposures

Main result up to now:

Momentum measurement through multiple scattering

(dedicated talk)